

# Remotely Operated Vehicles *Deep Discoverer* and *Seirios*

Remotely operated vehicles (ROV) *Deep Discoverer* and *Seirios* operate as a two-body system off NOAA Ship *Okeanos Explorer*. The system is owned by NOAA Ocean Exploration and developed, maintained, and operated by a team of engineers at the Global Foundation for Ocean Exploration. It's capable of exploring to depths as great as 6,000 meters, offering a wide range of surveying and sampling capabilities for exploring the deep ocean. The pair has completed over 400 dives together in the Pacific and Atlantic basins.

## Scientific Instrument Support

- Flexible telemetry and power system with spare gigabit Ethernet, high-speed serial, and fiber-optic connections available for equipment
- Switched power at various typical subsea voltages

## Configuration

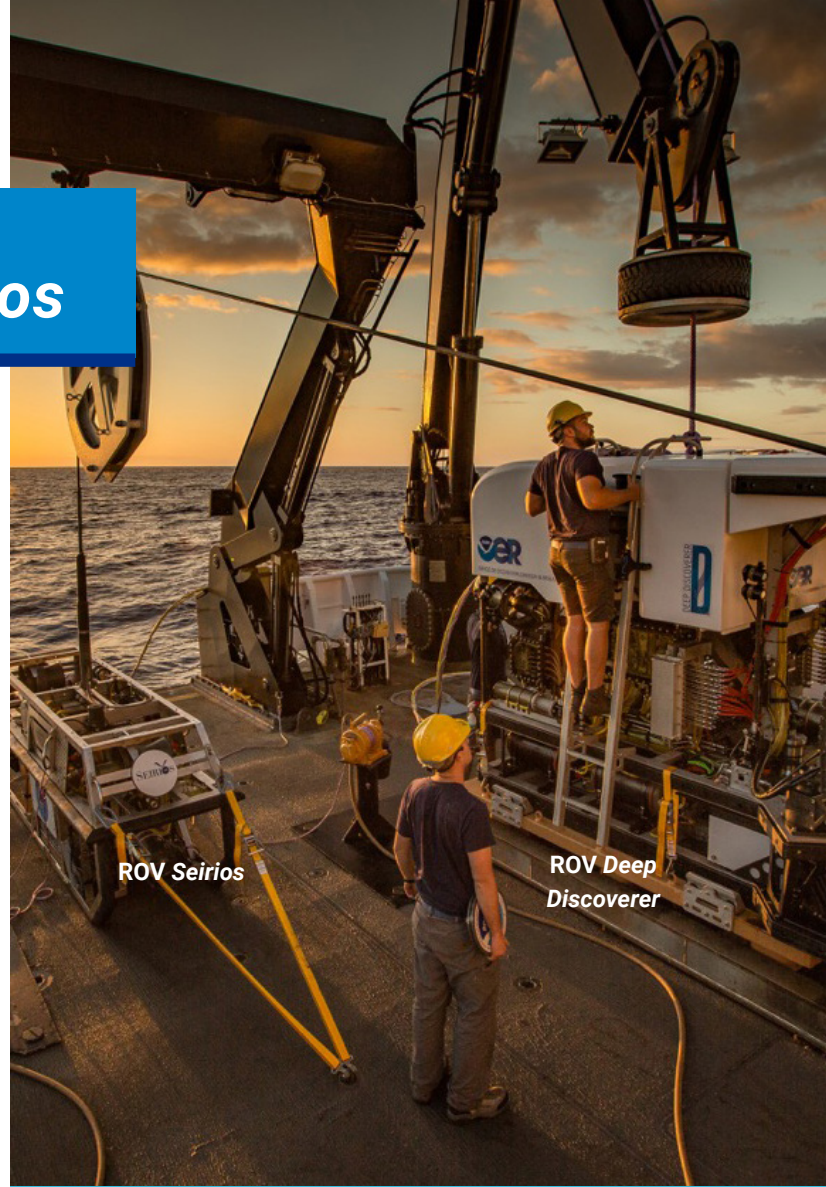
A 9,000-meter-long, 1.7-centimeter-wide electro-optical cable connects the system to the ship, providing power to the ROVs as well as a pathway for data transfer between the vehicles and the ship. The camera sled *Seirios* is directly tethered to the ship via this cable and is attached to *Deep Discoverer* via a 33-meter-long electro-optical neutral buoyancy cable.

This configuration allows *Seirios* to absorb the heave from the ship while keeping *Deep Discoverer* stable as it explores the ocean floor. The lights and cameras on *Seirios* give the ROV pilots a bird's eye view of *Deep Discoverer* and surrounding areas, literally shedding light on a dive site's features and inhabitants.

## Imaging Capabilities

Imaging is the main capability of the ROV system. There are 15 total video cameras between the two ROVs, including 10 high-definition cameras. *Deep Discoverer's* primary camera can fully zoom in on a 7.6-centimeter-long organism from 3 meters away. Two lasers, located 10 centimeters apart, are used to determine the scale of objects in *Deep Discoverer's* view.

46 LED lamps deliver more than 355,400 lumens of light, illuminating the otherwise dark ocean. *Deep Discoverer* has four specially fitted swing arms that allow pilots to maneuver light angles to hard-to-reach areas and to optimize camera views. Three LED light banks mounted on the back of *Seirios* are aimed forward and down to illuminate *Deep Discoverer* and the surrounding area from above.



ROV *Seirios*

ROV *Deep Discoverer*

Specification	<i>Deep Discoverer</i>	<i>Seirios</i>
Size (length, width, height)	3.2 meters, 2.0 meters, 2.6 meters	3.3 meters, 1.1 meters, 1.2 meters
Weight (in air)	4,400 kilograms	1,830 kilograms
Ascent/Descent Rate	30 meters/minute	30 meters/minute
Maximum Operating Depth	6,000 meters	6,000 meters
Propulsion	6 thrusters, 7.5 HP electric	2 thrusters, 7.5 HP electric

## Lighting and Imaging

### Deep Discoverer

- 28 Deep Sea Power and Light LED lamps (8 on swing arms)
- 3 high-definition Insite Pacific video cameras: Zeus Plus (tilt/18x optical zoom), its primary ROV camera, labeled ROVHD; Mini Zeus (pan/tilt); and Titan Plus (pan/tilt/zoom)
- 8 high-definition DeepSea Flexlink Multi SeaCams
- 1 custom packaged Canon R3 still camera with an RF24mm macro lens and high-definition video capability

### Seirios

- 18 LED lamps
- 1 high-definition Insite Pacific Zeus Plus video camera with tilt capability, its primary camera, labeled CPHD
- 4 high-definition DeepSea Flexlink Multi SeaCams

## Navigation

### Deep Discoverer

- iXSea Phins fiber optical/inertial navigation system (0.05° heading accuracy)
- Nortek DVL 500 Doppler velocity log (DVL), 500 kilohertz, 6,000-meter operational depth
- Control software supports high-resolution navigation using DVL bottom lock and Phins heading reference with an accuracy of 0.1% of distance traveled
- TrackLink 10000HA ultra-short baseline (USBL) acoustic tracking system with positioning accuracy of 0.25° (26 meters at 6,000 meters depth)
- Trittech PA500 altimeter, 0.3-50-meter range
- Paroscientific 8B7000-I depth sensor
- Lord MicroStrain 3DM inertial motion unit (IMU)

### Seirios

- TrackLink 10000HA USBL acoustic tracking system with positioning accuracy of 0.25° (26 meters at 6,000 meters depth)
- Trittech PA200 altimeter, 1-100-meter range
- Paroscientific 8B7000-I depth sensor
- Lord MicroStrain 3DM inertial motion unit (IMU)

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## Sampling and Sensing Capabilities

*Deep Discoverer* is capable of collecting up to 11 biological and geological samples and 5 water samples for eDNA analysis during each dive. Both vehicles are outfitted with scientific sensors to collect additional information about the ocean and to help characterize the areas explored.

## Sampling

### Deep Discoverer

- 1 hydraulic force feedback seven-function Kraft Predator manipulator arm
- 1 hydraulic seven-function Schilling Orion manipulator arm
- 4 bio boxes
- 2 rock boxes, 1 with a lid
- 1 rotary suction sampler with 5 2.7-liter sample jars
- 5 1.7-liter individually triggered Niskin bottles
- ~10 kilograms of payload available for samples

## Standard Sensors

- SeaBird SBE-911 Plus CTD (conductivity, temperature, and depth system) with dissolved oxygen, turbidity, and oxidation reduction potential sensors
- Trittech SeaKing DFS Dual frequency sector scan sonar, 200-meter range, 325 and 725 kilohertz
- Woods Hole Oceanographic Institution high-temperature probes, up to 400°C (*Deep Discoverer*)
- BlueView M900/2250 dual frequency multibeam sonar, 100-meter range, 15 hertz update rate, 130° field of view (*Deep Discoverer*)

## Data Availability

Video, imagery, environmental data, and samples collected are available through the NOAA and partner archives. To access these data and products, visit:

<https://oceanexplorer.noaa.gov/data/access/access.html>.

